

# Kapitel 3: Dynamic Programming

## Inhalt:

- Weighted Interval Scheduling
- Segmented Least Squares
- Knapsack Problem
- Sequence Alignment

# Knapsack Problem

## Knapsack problem.

- Given  $n$  objects and a "knapsack."
- Item  $i$  weights  $w_i > 0$  kilograms and has value  $v_i > 0$ .
- Knapsack has capacity of  $W$  kilograms.
- Goal: fill knapsack so as to maximize total value.

Ex: { 3, 4 } has value 40.

$W = 11$

Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

**Greedy:** repeatedly add item with maximum ratio  $v_i / w_i$ .

Ex: { 5, 2, 1 } achieves only value = 35  $\Rightarrow$  greedy not optimal.

# Dynamic Programming: False Start

Def.  $OPT(i)$  = max profit subset of items  $1, \dots, i$ .

- Case 1:  $OPT$  does not select item  $i$ .
  - $OPT$  selects best of  $\{ 1, 2, \dots, i-1 \}$
- Case 2:  $OPT$  selects item  $i$ .
  - accepting item  $i$  does not immediately imply that we will have to reject other items
  - without knowing what other items were selected before  $i$ , we don't even know if we have enough room for  $i$

Conclusion. Need more sub-problems!

## Dynamic Programming: Adding a New Variable

**Def.**  $OPT(i, w)$  = max profit subset of items 1, ..., i with weight limit w.

- Case 1:  $OPT$  does not select item  $i$ .
  - $OPT$  selects best of  $\{ 1, 2, \dots, i-1 \}$  using weight limit  $w$
- Case 2:  $OPT$  selects item  $i$ .
  - new weight limit =  $w - w_i$
  - $OPT$  selects best of  $\{ 1, 2, \dots, i-1 \}$  using this new weight limit

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i-1, w) & \text{if } w_i > w \\ \max \{ OPT(i-1, w), v_i + OPT(i-1, w - w_i) \} & \text{otherwise} \end{cases}$$

# Knapsack Problem: Bottom-Up

Knapsack. Fill up an  $n$ -by- $W$  array.

```
Input:  $n, W, w_1, \dots, w_n, v_1, \dots, v_n$ 

for  $w = 0$  to  $W$ 
   $M[0, w] = 0$ 

for  $i = 1$  to  $n$ 
  for  $w = 1$  to  $W$ 
    if ( $w_i > w$ )
       $M[i, w] = M[i-1, w]$ 
    else
       $M[i, w] = \max \{M[i-1, w], v_i + M[i-1, w-w_i]\}$ 

return  $M[n, W]$ 
```

# Knapsack Algorithm

$\xrightarrow{\hspace{10em} W + 1 \hspace{10em} \xrightarrow{\hspace{10em}}$

		0	1	2	3	4	5	6	7	8	9	10	11
$n + 1$	$\phi$	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
	{1, 2}	0	1	6	7	7	7	7	7	7	7	7	7
	{1, 2, 3}	0	1	6	7	7	18	19	24	25	25	25	25
	{1, 2, 3, 4}	0	1	6	7	7	18	22	24	28	29	29	40
	{1, 2, 3, 4, 5}	0	1	6	7	7	18	22	28	29	34	35	40

OPT: { 4, 3 }  
 value = 22 + 18 = 40

W = 11

Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

# Knapsack Problem: Running Time

Running time.  $\Theta(nW)$ .

- Not polynomial in input size!
- "Pseudo-polynomial."
- Decision version of Knapsack is NP-complete.

**Knapsack approximation algorithm.** There exists a polynomial algorithm that produces a feasible solution that has value within 0.01% of optimum.

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# String Similarity

How similar are two strings?

- **ocurrance**
- **occurrence**

o	c	u	r	r	a	n	c	e	-
o	c	c	u	r	r	e	n	c	e

6 mismatches, 1 gap

o	c	-	u	r	r	a	n	c	e
o	c	c	u	r	r	e	n	c	e

1 mismatch, 1 gap

o	c	-	u	r	r	-	a	n	c	e
o	c	c	u	r	r	e	-	n	c	e

0 mismatches, 3 gaps

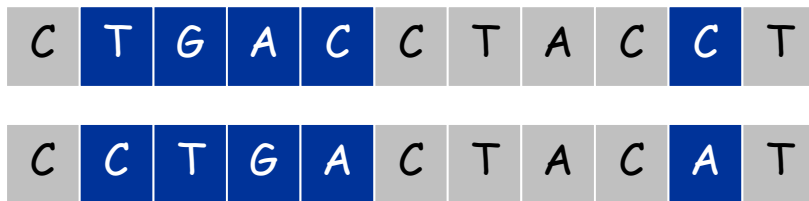
# Edit Distance

## Applications.

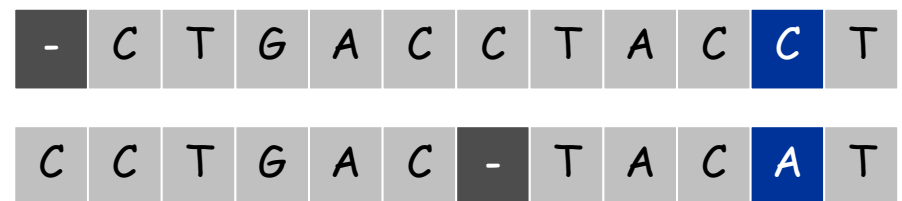
- Basis for Unix diff.
- Speech recognition.
- Computational biology.

Edit distance. [Levenshtein 1966, Needleman-Wunsch 1970]

- Gap penalty  $\delta$ ; mismatch penalty  $\alpha_{pq}$ .
- Cost = sum of gap and mismatch penalties.



$$\alpha_{TC} + \alpha_{GT} + \alpha_{AG} + 2\alpha_{CA}$$



$$2\delta + \alpha_{CA}$$

# Sequence Alignment

**Goal:** Given two strings  $X = x_1 x_2 \dots x_m$  and  $Y = y_1 y_2 \dots y_n$  find alignment of minimum cost.

**Def.** An **alignment**  $M$  is a set of ordered pairs  $x_i - y_j$  such that each item occurs in at most one pair and no crossings.

**Def.** The pair  $x_i - y_j$  and  $x_{i'} - y_{j'}$  **cross** if  $i < i'$ , but  $j > j'$ .

$$\text{cost}(M) = \underbrace{\sum_{(x_i, y_j) \in M} \alpha_{x_i y_j}}_{\text{mismatch}} + \underbrace{\sum_{i: x_i \text{ unmatched}} \delta + \sum_{j: y_j \text{ unmatched}} \delta}_{\text{gap}}$$

**Ex:** CTACCG vs. TACATG.

**Sol:**  $M = x_2 - y_1, x_3 - y_2, x_4 - y_3, x_5 - y_4, x_6 - y_6$ .

$x_1$	$x_2$	$x_3$	$x_4$	$x_5$		$x_6$
C	T	A	C	C	-	G
	T	A	C	A	T	G
	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$	$y_6$

## Sequence Alignment: Problem Structure

- Def.**  $OPT(i, j)$  = min cost of aligning strings  $x_1 x_2 \dots x_i$  and  $y_1 y_2 \dots y_j$ .
- Case 1:  $OPT$  matches  $x_i$ - $y_j$ .
    - pay cost for  $x_i$ - $y_j$  + min cost of aligning two strings  $x_1 x_2 \dots x_{i-1}$  and  $y_1 y_2 \dots y_{j-1}$
  - Case 2a:  $OPT$  leaves  $x_i$  unmatched.
    - pay gap for  $x_i$  and min cost of aligning  $x_1 x_2 \dots x_{i-1}$  and  $y_1 y_2 \dots y_j$
  - Case 2b:  $OPT$  leaves  $y_j$  unmatched.
    - pay gap for  $y_j$  and min cost of aligning  $x_1 x_2 \dots x_i$  and  $y_1 y_2 \dots y_{j-1}$

$$OPT(i, j) = \begin{cases} j\delta & \text{if } i = 0 \\ \min \begin{cases} \alpha_{x_i y_j} + OPT(i-1, j-1) \\ \delta + OPT(i-1, j) \\ \delta + OPT(i, j-1) \end{cases} & \text{otherwise} \\ i\delta & \text{if } j = 0 \end{cases}$$

# Sequence Alignment: Algorithm

```
Sequence-Alignment(m, n, x1x2...xm, y1y2...yn, δ, α) {  
  for j = 0 to m  
    M[0, j] = jδ  
  for i = 0 to n  
    M[i, 0] = iδ  
  
  for i = 1 to m  
    for j = 1 to n  
      M[i, j] = min(α[xi, yj] + M[i-1, j-1],  
                   δ + M[i-1, j],  
                   δ + M[i, j-1])  
  
  return M[m, n]  
}
```

**Analysis.**  $\Theta(mn)$  time and space.

English words or sentences:  $m, n \leq 10$ .

Computational biology:  $m = n = 100,000$ . 10 billions ops OK, but 10 GB array?

## Sequence Alignment: Linear Space

Q. Can we avoid using quadratic **space**?

Easy. Optimal **value** in  $O(m + n)$  space and  $O(mn)$  time.

- Compute  $\text{OPT}(i, \cdot)$  from  $\text{OPT}(i-1, \cdot)$ .
- No longer a simple way to recover alignment itself.

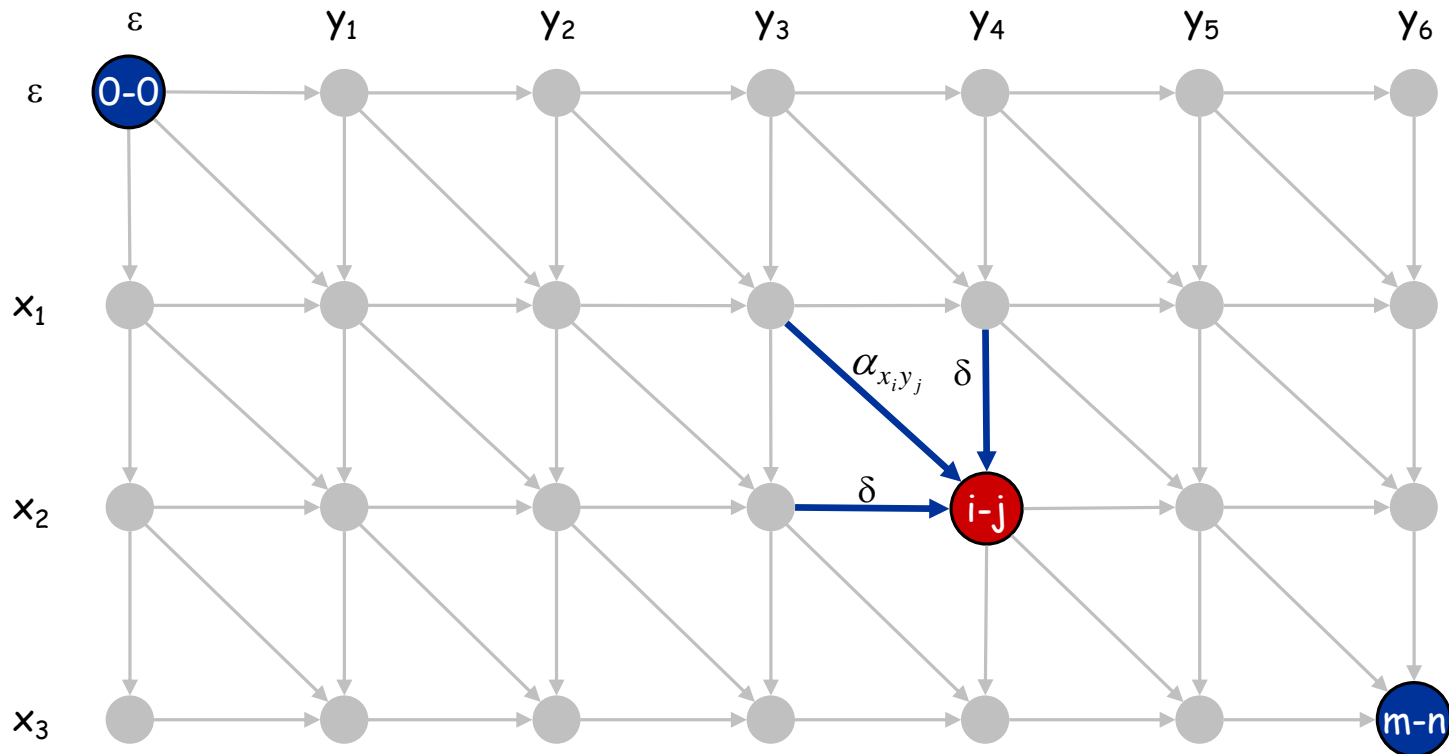
Theorem. [Hirschberg 1975] Optimal **alignment** in  $O(m + n)$  space and  $O(mn)$  time.

- Clever combination of divide-and-conquer and dynamic programming.
- Inspired by idea of Savitch from complexity theory.

# Sequence Alignment: Linear Space

## Edit distance graph.

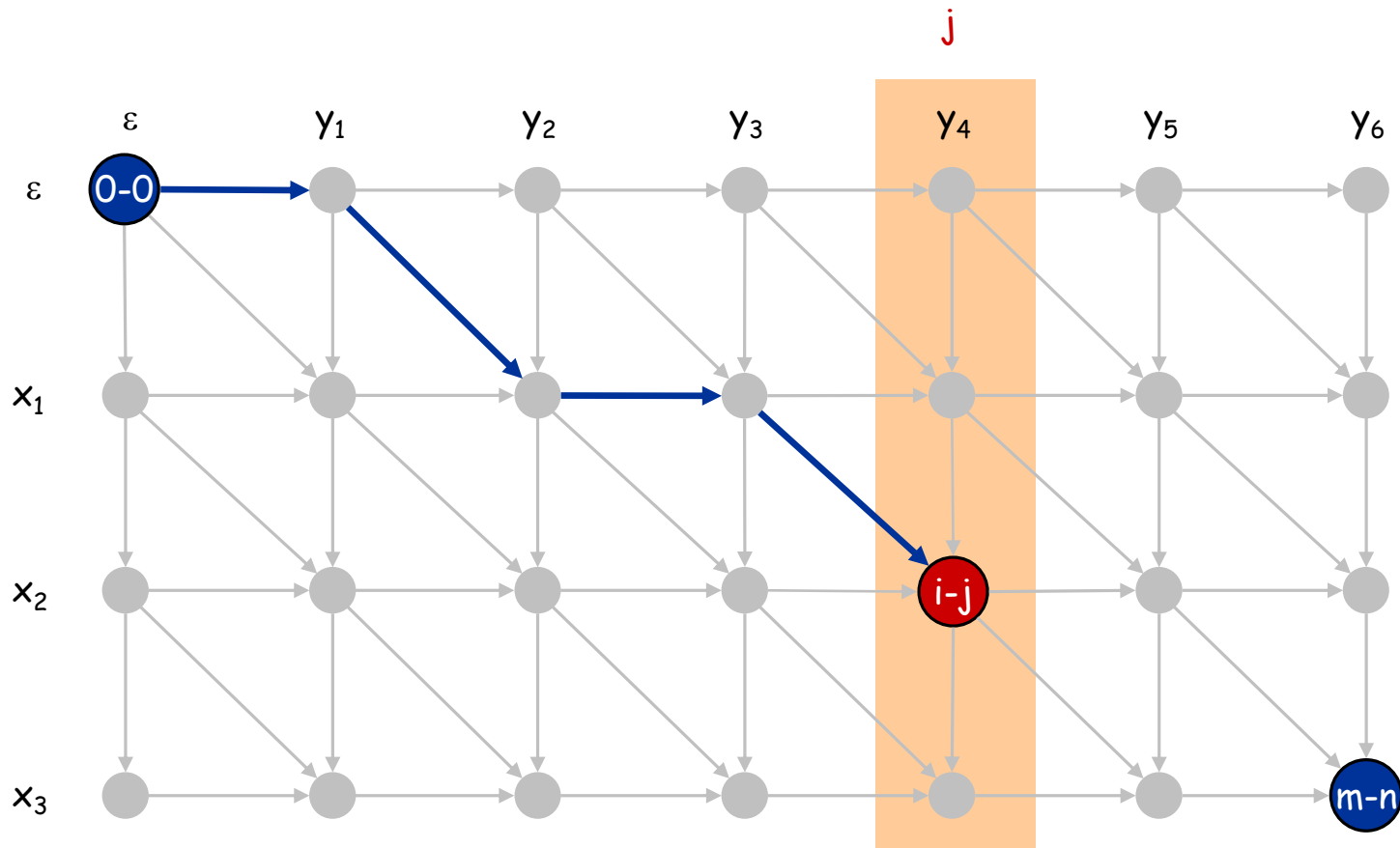
- Let  $f(i, j)$  be shortest path from  $(0,0)$  to  $(i, j)$ .
- Observation:  $f(i, j) = \text{OPT}(i, j)$ .



# Sequence Alignment: Linear Space

Edit distance graph.

- Let  $f(i, j)$  be shortest path from  $(0,0)$  to  $(i, j)$ .
- Can compute  $f(\cdot, j)$  for any  $j$  in  $O(mn)$  time and  $O(m + n)$  space.

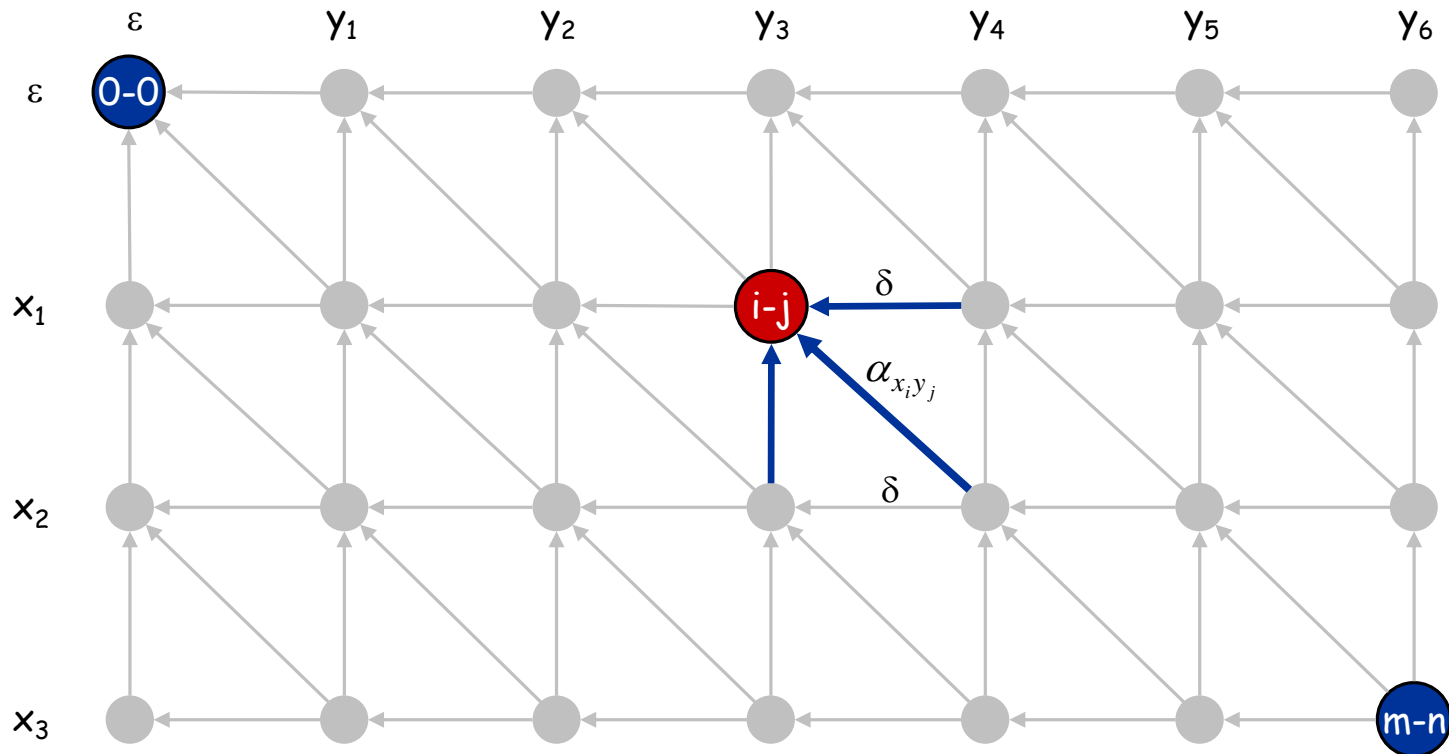




# Sequence Alignment: Linear Space

## Edit distance graph.

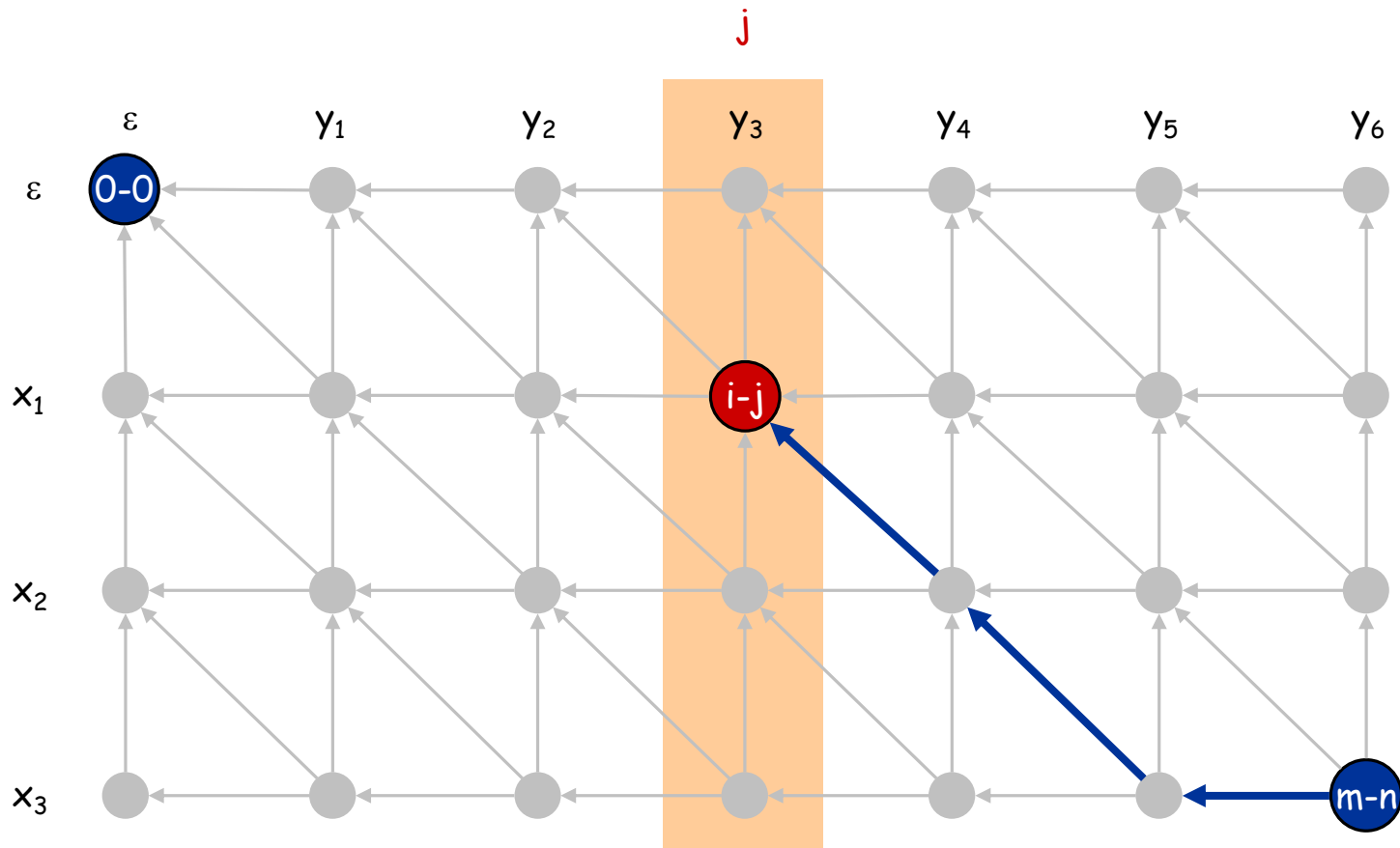
- Let  $g(i, j)$  be shortest path from  $(i, j)$  to  $(m, n)$ .
- Can compute by reversing the edge orientations and inverting the roles of  $(0, 0)$  and  $(m, n)$



# Sequence Alignment: Linear Space

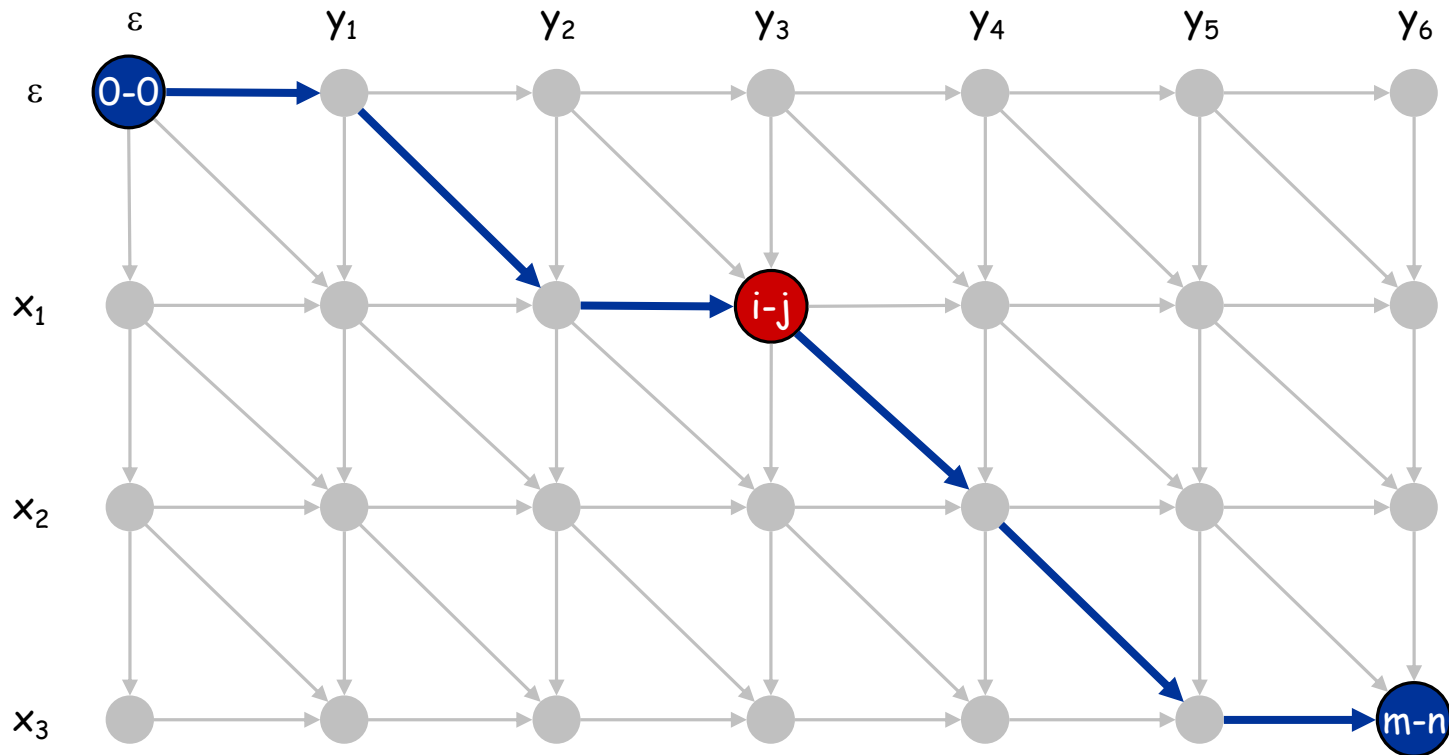
Edit distance graph.

- Let  $g(i, j)$  be shortest path from  $(i, j)$  to  $(m, n)$ .
- Can compute  $g(\cdot, j)$  for any  $j$  in  $O(mn)$  time and  $O(m + n)$  space.



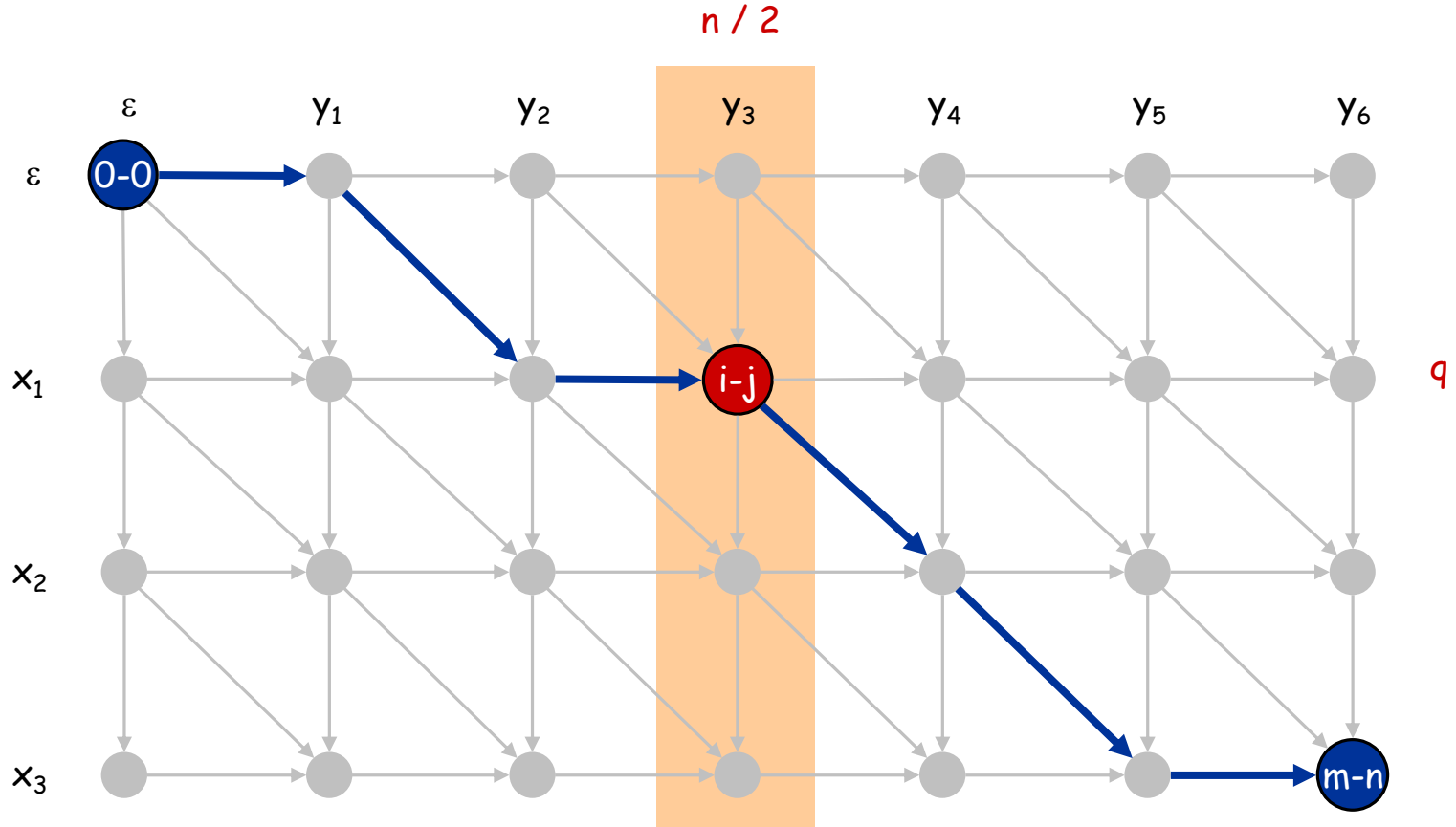
# Sequence Alignment: Linear Space

**Observation 1.** The cost of the shortest path that uses  $(i, j)$  is  $f(i, j) + g(i, j)$ .



# Sequence Alignment: Linear Space

**Observation 2.** let  $q$  be an index that minimizes  $f(q, n/2) + g(q, n/2)$ . Then, the shortest path from  $(0, 0)$  to  $(m, n)$  uses  $(q, n/2)$ .

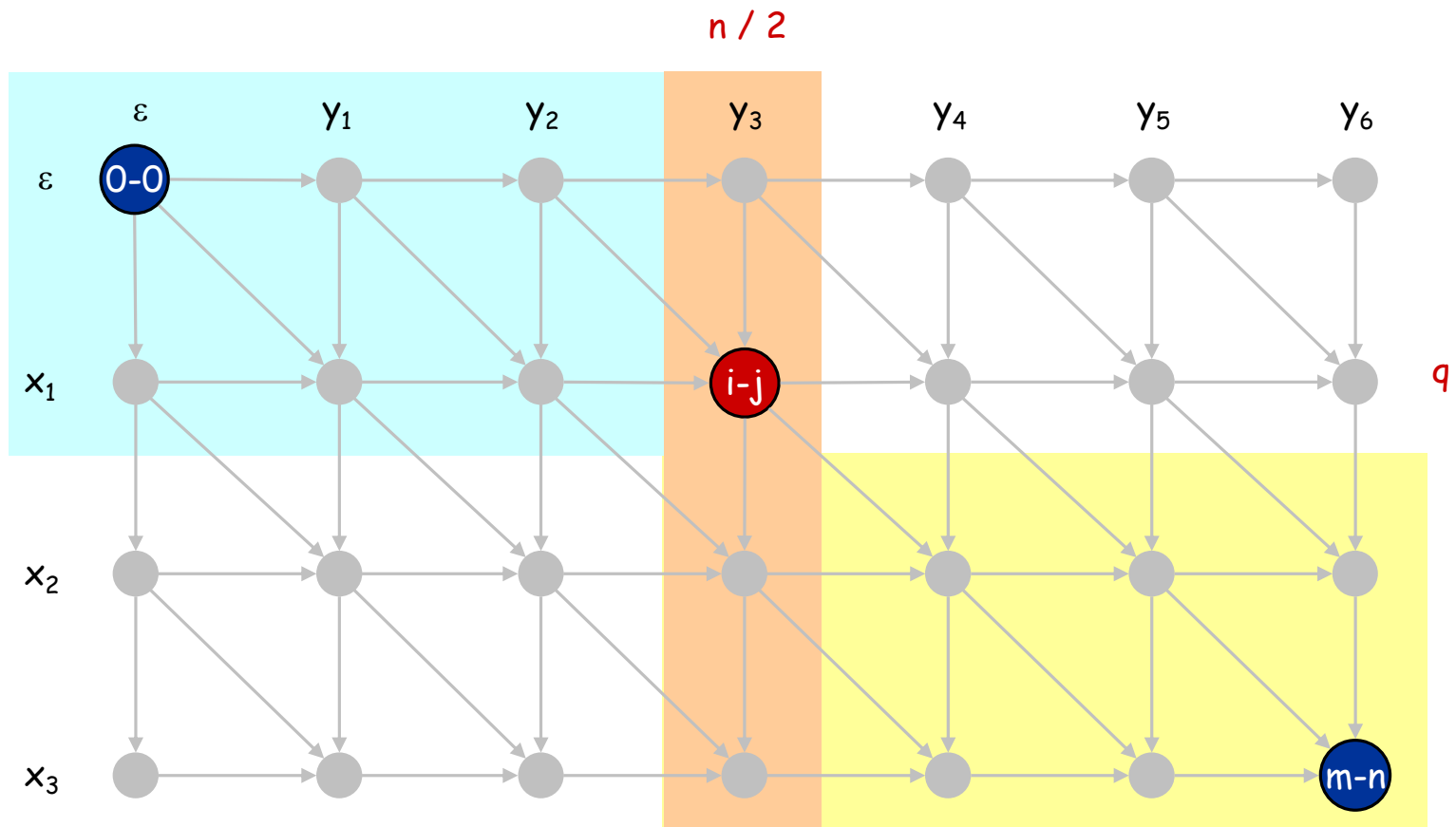


# Sequence Alignment: Linear Space

**Divide:** find index  $q$  that minimizes  $f(q, n/2) + g(q, n/2)$  using DP.

- Align  $x_q$  and  $y_{n/2}$ .

**Conquer:** recursively compute optimal alignment in each piece.



## Sequence Alignment: Running Time Analysis Warmup

**Theorem.** Let  $T(m, n)$  = max running time of algorithm on strings of length at most  $m$  and  $n$ .  $T(m, n) = O(mn \log n)$ .

$$T(m, n) \leq 2T(m, n/2) + O(mn) \Rightarrow T(m, n) = O(mn \log n)$$

**Remark.** Analysis is not tight because two sub-problems are of size  $(q, n/2)$  and  $(m - q, n/2)$ . In next slide, we save  $\log n$  factor.

# Sequence Alignment: Running Time Analysis

**Theorem.** Let  $T(m, n)$  = max running time of algorithm on strings of length  $m$  and  $n$ .  $T(m, n) = O(mn)$ .

**Pf.** (by induction on  $n \cdot m$ )

- $O(mn)$  time to compute  $f(\cdot, n/2)$  and  $g(\cdot, n/2)$  and find index  $q$ .
- $T(q, n/2) + T(m - q, n/2)$  time for two recursive calls.
- Choose constant  $c$  so that:

$$T(m, 2) \leq cm$$

$$T(2, n) \leq cn$$

$$T(m, n) \leq cmn + T(q, n/2) + T(m - q, n/2)$$

- Base cases:  $m = 2$  or  $n = 2$ .
- Inductive hypothesis:  $T(m', n') \leq 2cm'n'$ .

$$\begin{aligned} T(m, n) &\leq T(q, n/2) + T(m - q, n/2) + cmn \\ &\leq 2cqn/2 + 2c(m - q)n/2 + cmn \\ &= cqn + cmn - cqn + cmn \\ &= 2cmn \end{aligned}$$

# Dynamic Programming Summary

## Recipe.

- Characterize structure of problem.
- Recursively define value of optimal solution.
- Compute value of optimal solution.
- Construct optimal solution from computed information.

## Dynamic programming techniques.

- Binary choice: weighted interval scheduling.
- Multi-way choice: segmented least squares. ←
- Adding a new variable: knapsack.
- Dynamic programming over intervals: RNA secondary structure.

Viterbi algorithm for HMM also uses DP to optimize a maximum likelihood tradeoff between parsimony and accuracy

← CKY parsing algorithm for context-free grammar has similar structure

Top-down vs. bottom-up: different people have different intuitions.



# Fragen?

